

Azimuth Modulation of C-band Sigma-0 Over Antarctica from ASCAT Data

15 Jan 2011

David Long
Brigham Young University

Strong, steady winds give rise to coherent structuring of snow in Antarctica. Sastrugi and the Antarctic Megadunes are particular examples of this, but such structuring extends below the surface via wind-driven preferential deposition and inter-annual layering. Coupled with local topography, these effects introduce a dependency of radar backscatter on the azimuth direction of the observations. This is termed 'azimuth modulation'. Microwave azimuth modulation was first explored by Long and Drinkwater (2000) for passive microwave measurements and the Ku-band NASA Scatterometer (NSCAT) and the C-band ERS-1/2 scatterometers. These initial studies revealed that the azimuth dependence of the normalized radar cross section (σ_0) can be quite large and is closely correlated with the wind direction. In fact, they showed that the dominant wind direction could be derived with surprising accuracy from the azimuth dependency of the scatterometer-observed backscatter. The analysis has been extended to Greenland (Ashcraft and Long, 2005; 2006), and can even be applied in the Sahara desert (Stephen and Long, 2005)!

The observed azimuth modulation of radar backscatter has profound implications for other radar sensors as well, including synthetic aperture radar (SAR) systems. When multiple observations or images are compared, if the azimuth angles of the observations are not identical, there may be a difference in the observed surface σ_0 . This could easily be misinterpreted as a change in the surface, when it really is merely due to the differences in the σ_0 values at different azimuth angles. This may be particularly important when studying long-term changes in the ice sheet.

To help ameliorate this concern, we have generated a data product derived from scatterometer observations that exploits the multi-azimuth observation capability of the scatterometer to estimate the azimuth modulation of the ice sheet. This data set can be used to compute an estimate of the azimuth modulation based on the differences in the azimuth angles of the sensor observation. This value can be used to "correct" the observation to eliminate (or at least minimize) the potential for falsely ascribing an observed change in σ_0 that is due to azimuth modulation, to some other source, e.g. increased melting or accumulation.

While very well calibrated, compared to SARs, scatterometers have much coarser resolution. To better enable our product to support this correction process for SARs, we use resolution enhancement techniques to estimate the spatial variation of the azimuth modulation at the finest possible spatial scale [see (Long and Drinkwater, 2000)]. Effectively, an AVE-type algorithm is employed in computing the azimuth modulation characteristics on a fine-scale (at least for a scatterometer) grid with a resolution 4.45 km in a polar stereographic projection.

The particular azimuth sampling characteristics of NSCAT and ERS-1/2 limited the analysis to second order dependence on the azimuth angle. However, the rotating pencil-beam SeaWinds scatterometer and the dual-side, three-beam nature of the ESA Advanced Scatterometer (ASCAT) permit extension of the analysis to fourth order. This better models the observed azimuth modulation in most areas of Antarctica.

In general, the azimuth modulation is a function of incidence angle (Long and Drinkwater, 2000);

however, here we consider a simplified form that is not dependent on incidence angle. At a given location the sigma-0 (in dB) is written as,

$$\sigma^o = a + b(\theta - 40) + \varepsilon + \sigma_{az}^o(\varphi) \quad (1)$$

where a is the normalized radar cross-section normalized to a 40 deg incidence angle, b is the slope of sigma-0 versus incidence angle, θ is incidence angle in deg, ε is the residual error, and the final term is the azimuth modulation as a function of the azimuth angle φ of the microwave look direction relative to north. This definition of azimuth angle is used for convenience since the local slope can be folded into the azimuth modulation and so not explicitly be needed in computing the geometry (Long and Drinkwater, 2000). For this paper the fourth-order azimuth modulation term is expressed as

$$\sigma_{az}^o(\varphi) = \sum_{k=1}^4 m_k \cos(\varphi - \phi_k) \quad (2)$$

where m_k and ϕ_k as the azimuth modulation parameters estimated from ASCAT data for the particular location. The m_k parameter is the magnitude of the k^{th} order modulation while ϕ_k is the phase angle parameter. For historical reasons and to fit within the standard BYU .sir file naming scheme, each azimuth modulation parameter is given single letter name as indicated in Table 1

Table 1. Azimuth modulation coefficients and .sir file designation separated by a colon.

Index	Magnitude	Phase
1	$m_1 : q$	$\phi_1 : r$
2	$m_2 : s$	$\phi_2 : t$
3	$m_3 : Q$	$\phi_3 : R$
4	$m_4 : S$	$\phi_4 : T$

We have found that the C-band azimuth modulation parameters do not exhibit significant seasonal change in areas that do not experience melt, and have minimal variation over the mission. For areas that experience seasonal melt, the azimuth modulation tends to be very small. Thus, for now we have provided a single, time-constant set of parameters. We believe that is adequate for a first-order correction for the effects of azimuth modulation. A more comprehensive analysis will be included in a paper currently in preparation. The prototype azimuth modulation correction data set is derived from 30 days (mid winter, JD 172-212) of ASCAT data collected in 2010. Images of model parameters for this data set are provided in the Appendix. To generate estimates for each azimuth modulation coefficient, the a and b coefficients are first separately estimated for each pixel using the AVE algorithm. The other coefficients are then estimated using a least-squares algorithm. To reduce noise, median filtering is one on the images. (A much more detailed description of the derivation is contained in the paper in preparation.)

ASCAT employs six antenna beams that collect data over a 20-65 deg incidence angle range on each side of the nadir track (ASCAT, 2009). Combining multiple passes, each pixel location in the 4.45 km grid is observed multiple times at different azimuth and incidence angles. Unfortunately, the region near the pole is observed by only one side of the spacecraft and thus has significantly few azimuth angle observations. This degrades the accuracy of the azimuth modulation parameters for latitudes south of approximately 78.25S falls off. North of this line, however, the estimates appear to be quite accurate. Evidence of this occurs in the spatial consistency of the estimates (see Fig. 4 and other examples in the Appendix).

To illustrate the modulation and model fit, we extracted all raw ASCAT measurements whose centers fall within a box defined by [124.3E to 123.7E, 70.4S to 70.1 S]. Figure 1 shows the ASCAT a image and the location of this study area. Movement of sea ice during the time period blurs the region outside of the continental area. Note that key topographical features are clearly evident, including the megadune region, summit, various ice shelves and mountains. The brightest regions are those along the coast which experience annual melting, i.e. the percolation zone. In the percolation zone, buried ice glands increase the volume backscatter, resulting in a high backscatter.

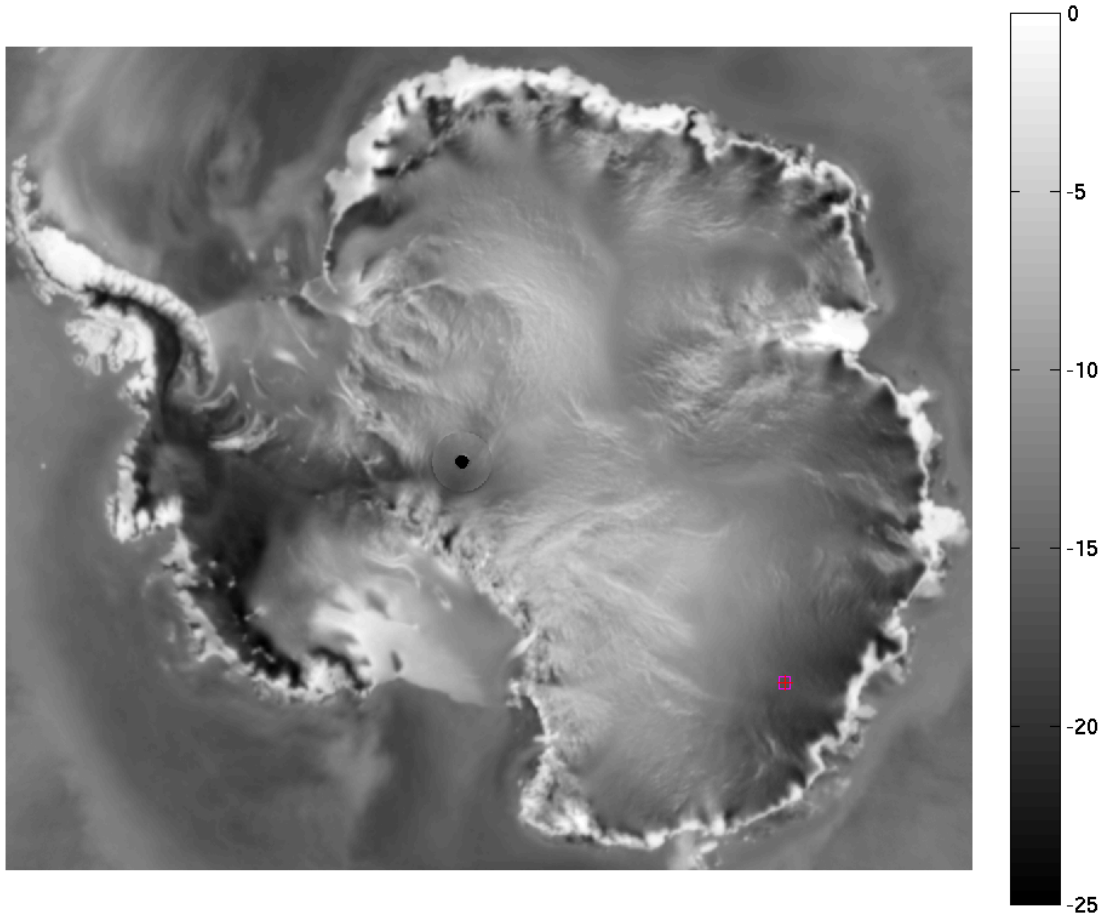


Figure 1. ASCAT C-band sigma-0 in dB normalized to a 40 degree incidence angle (termed 'a'). The red box shows a particular study location.

The raw measurements extracted from the study region are incidence angle corrected using the reported incidence angle and the b coefficient computed using linear regression of the raw data. The incidence-angle corrected values are shown in Fig. 2 as cyan dots. The particular distribution of azimuth angles varies with location, but this is a typical case. The fourth-order azimuth modulation computed from the coefficients stored in the data set for the pixel at the center of this location is shown as the solid line. Generally the curve fits the data well, though there some residual unmodelled error is apparent from -100 deg through about -50 deg. Note that magnitude of the azimuth modulation is ± 6 dB, distinctly non-negligible! The modulation curve by itself is shown in Fig. 3.

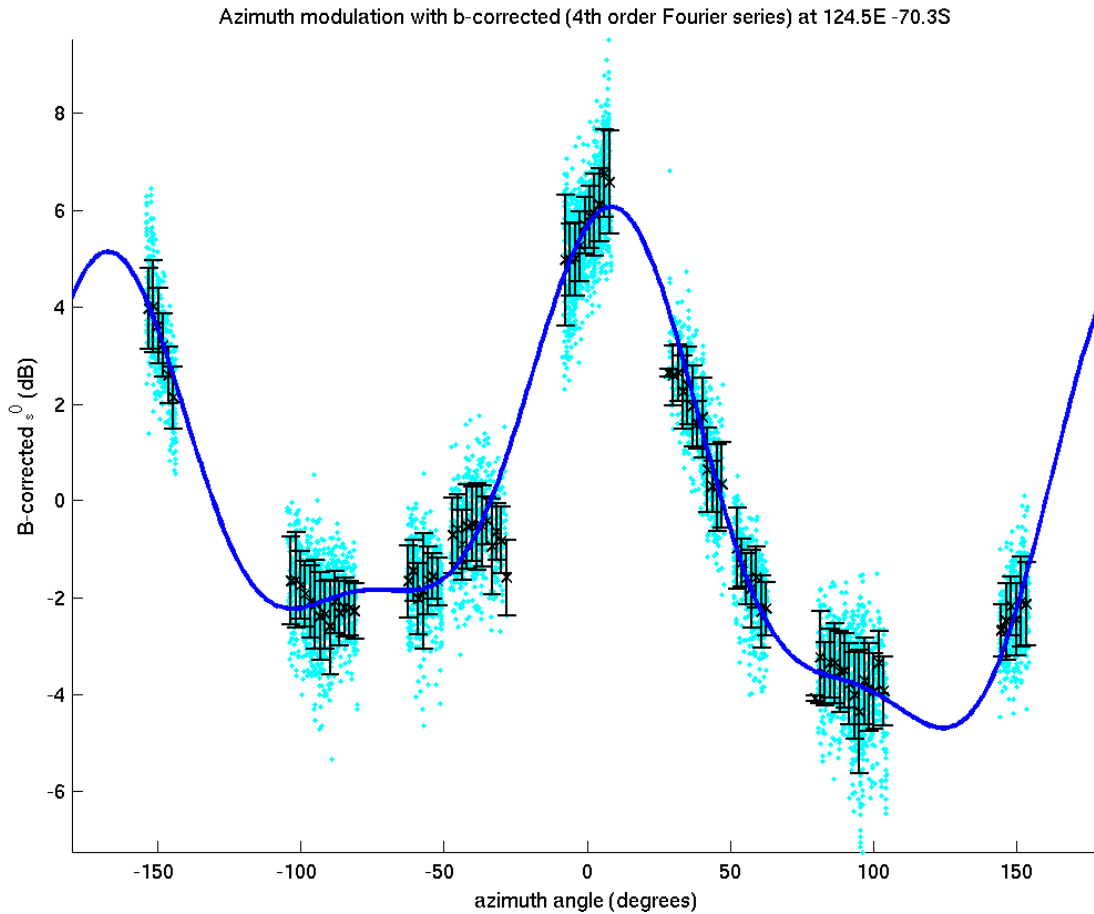


Figure 2. Scatterplot of incidence angle normalized ASCAT measurements plotted with respect to azimuth angle relative to north. These are binned in to small azimuth angle bins and the mean and standard deviation computed. These are shown as error bars. The sold blue line shows the fourth-order Fourier series fit from the BYU ASCAT modulation files.

In most areas of Antarctica, the azimuth modulation is sufficiently large that it should not be neglected when doing change detection. The proposed procedure to compensate for azimuth modulation is now described. For each location of interest (e.g. SAR image pixel), the azimuth angle relative to north of the microwave illumination is computed. The BYU azimuth modulation images are interpolated to the location and Eq. (2) computed. This yields an estimate of the azimuth modulation. We evaluating potential change between two different images, the difference in the azimuth modulation should be computed an included in the difference computation to estimate the change due to the only to the azimuth modulation. The residual difference is then the true change in backscatter.

I recognize that if the surface really did change (e.g. due to accumulation changes), that it is possible that azimuth modulation parameters may have changed as well. Further investigation of these locations is warranted. We can generate careful time series. However, to first-order based on our observations so far, changes in azimuth modulation appear to be small. For now, I recommend assuming the modulation is constant.

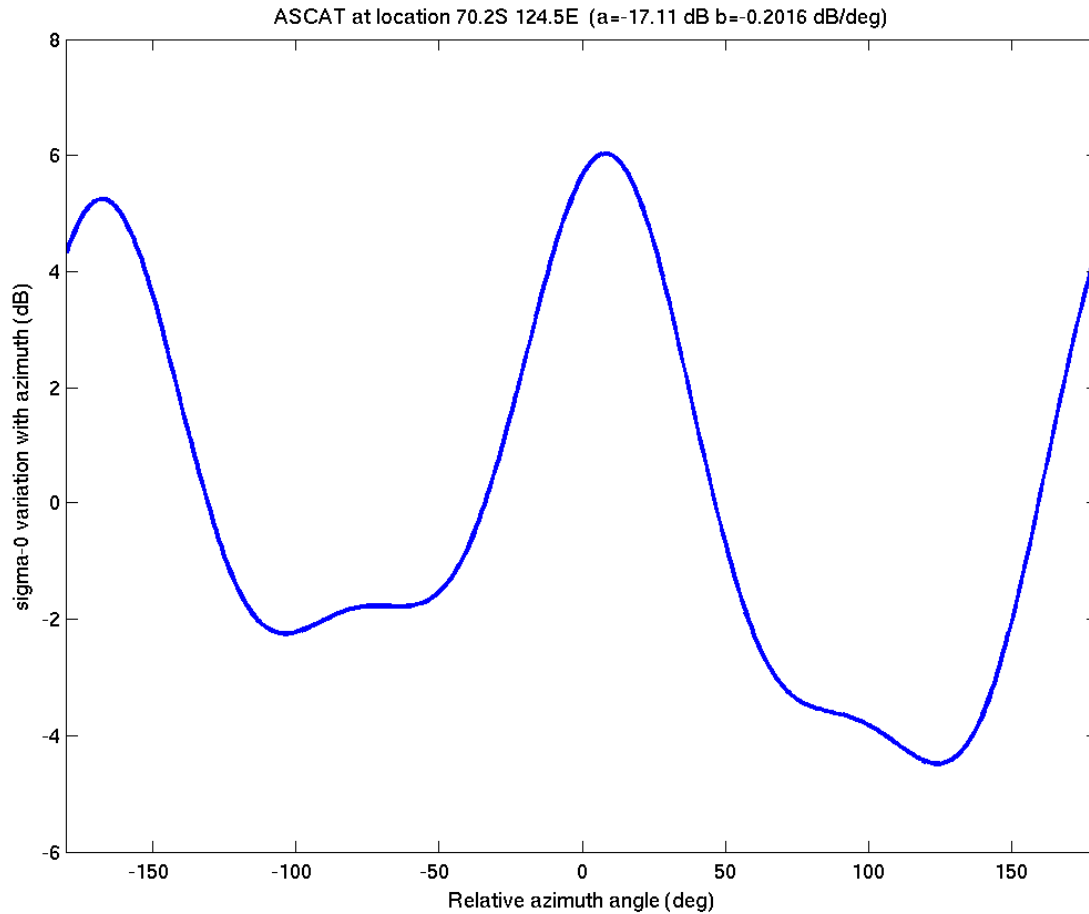


Figure 3. Plot of the fourth-order azimuth modulation of ASCAT C-band sigma-0 computed from the BYU ASCAT modulation files.

I have posted data files containing the azimuth modulation parameters in (gzipped) BYU .SIR file format on our anonymous ftp site at <ftp://scp.byu.edu.edu/outgoing/data/ts/azmod/> This directory also includes a matlab script (studyarea.m) that illustrates how to read, plot, and compute the azimuth modulation. The subroutines this script calls are available in the software area on our ftp site. If you have any questions, let me know.

As previously noted, the scatterometer observations extend from somewhat less than 20 deg incidence angle to nearly 65 deg. The azimuth modulation data set is optimized at a 40 deg incidence angle, which is appropriate for scatterometer observations. Since SAR observations tend to be at much lower incidence angles, some error can be expected. It is possible, however, to derive coefficients optimized for use at a lower incidence angle, though this would be limited by the incidence angles of the available scatterometer observations

ASCAT H-pol q (1st Az Har) (msfa-q-Ant10-182-212.sir) in dB

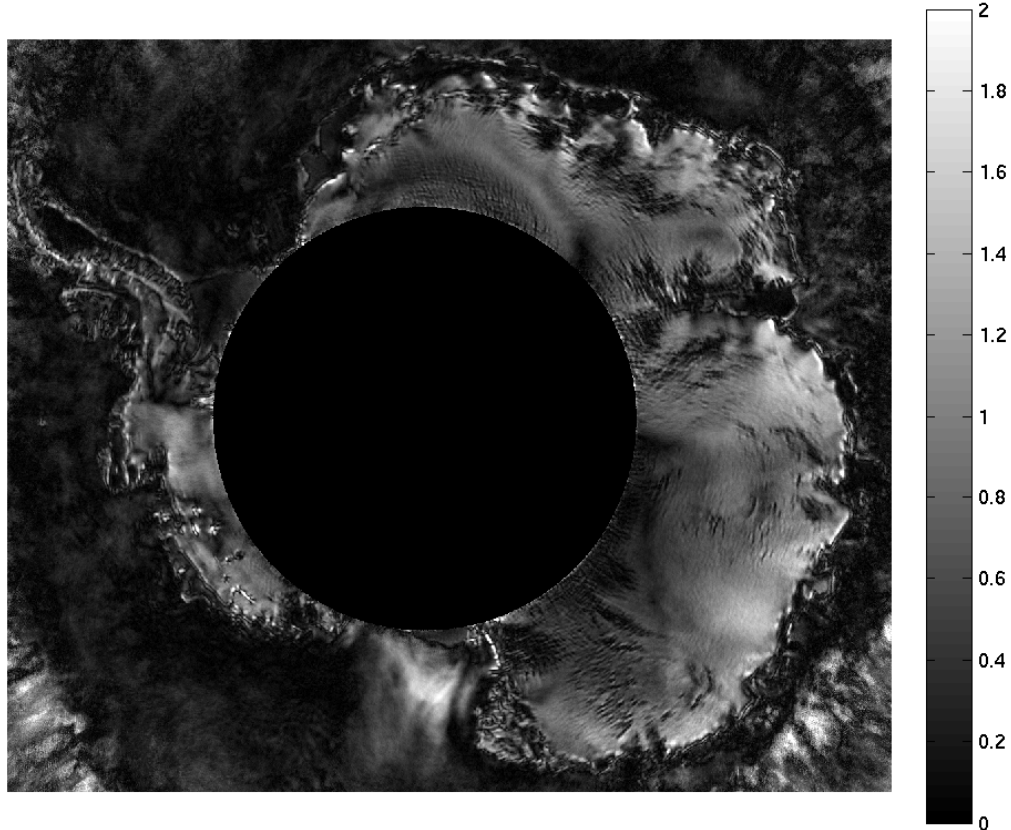


Figure 4. Image of the first-order magnitude azimuth modulation parameter with the “limited azimuth zone” indicated with a black circle. In this zone, the accuracy of the fourth-order model is reduced, see text.

References

ASCAT Users Manual, EUMETSAT, Aug. 2009.

I.S. Ashcraft and D.G. Long, 2006. Relating Microwave Backscatter Azimuth Modulation to Surface Properties of the Greenland Ice Sheet, *Journal of Glaciology*, 52(177), 257-266.

I.S. Ashcraft and D.G. Long, 2005. Observation and Characterization of Radar Backscatter over Greenland," *IEEE Transactions on Geoscience and Remote Sensing*, 43(2), 237-246.

D.G. Long and M.R. Drinkwater, 2000. Azimuth Variation in Microwave Scatterometer and Radiometer Data Over Antarctica, *IEEE Transactions on Geoscience and Remote Sensing*, 38(4), 1857-1870.

H. Stephen and D.G. Long, 2005. Microwave Backscatter Modeling of Erg Surfaces in the Sahara Desert, *IEEE Transactions on Geoscience and Remote Sensing*, 43(2), 238-247.

Appendix

This appendix illustrates the various coefficients of ASCAT 4th order azimuth modulation dataset. The various terms in the model are described in Eq. 1 in the main text.

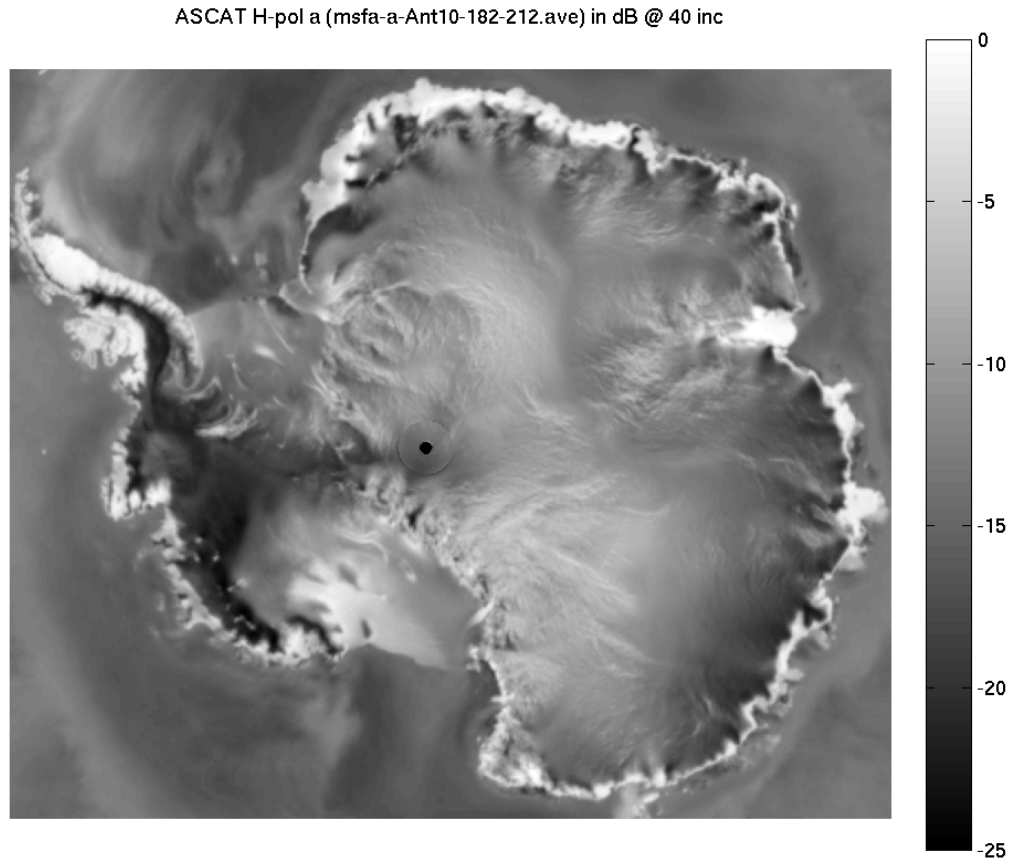


Fig. A.1 ASCAT C-band sigma-0 in dB normalized to a 40 degree incidence angle (termed 'a'). Accuracy is reduced for latitudes less than 88.5S due to inadequate coverage and no estimate is possible for latitudes less than approximately 88.7S.

ASCAT H-pol b (msfa-b-Ant10-182-212.ave) in dB/deg

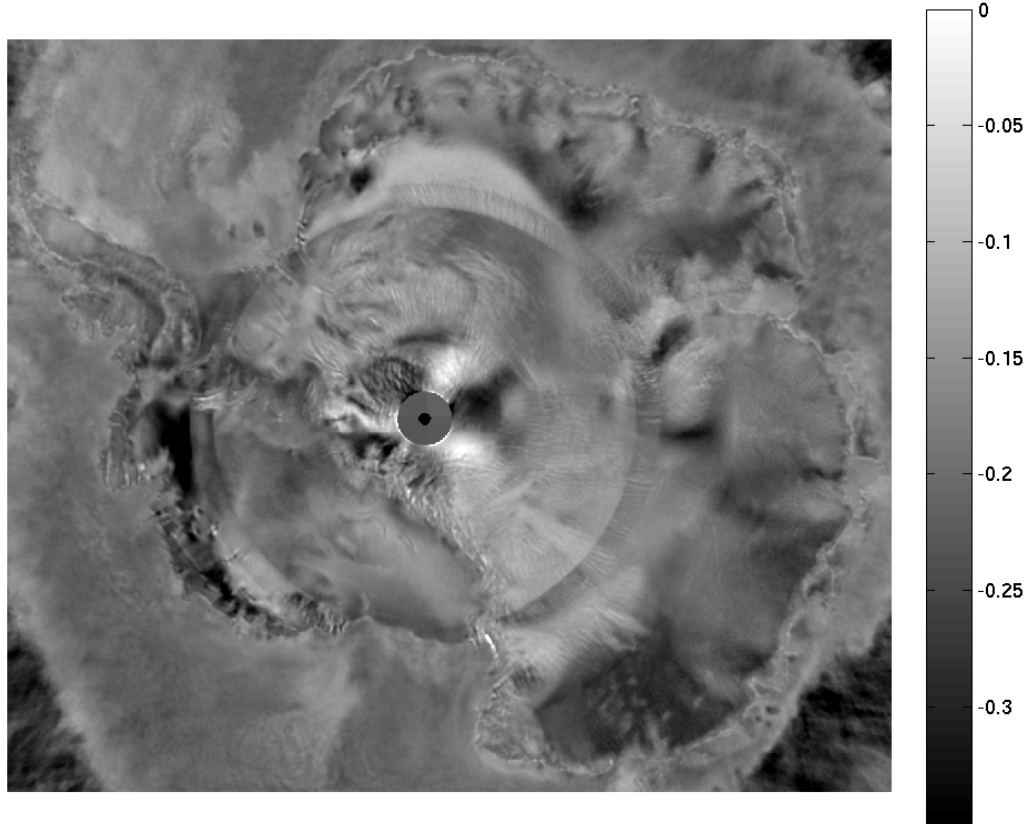


Fig. A.2 ASCAT C-band slope of sigma-0 in dB/deg at a 40 degree incidence angle (termed 'b'). For latitudes less than approximately 78.25S, the distribution of measurements in incidence is altered since all the observations of a given point are limited to a single side of the spacecraft, resulting in a visible transition band and reduced accuracy near the pole. No estimates are possible for latitudes less than 88.5S due to lack of coverage.

ASCAT H-pol q (1st Az Har) (msfa-q-Ant10-182-212.sir) in dB

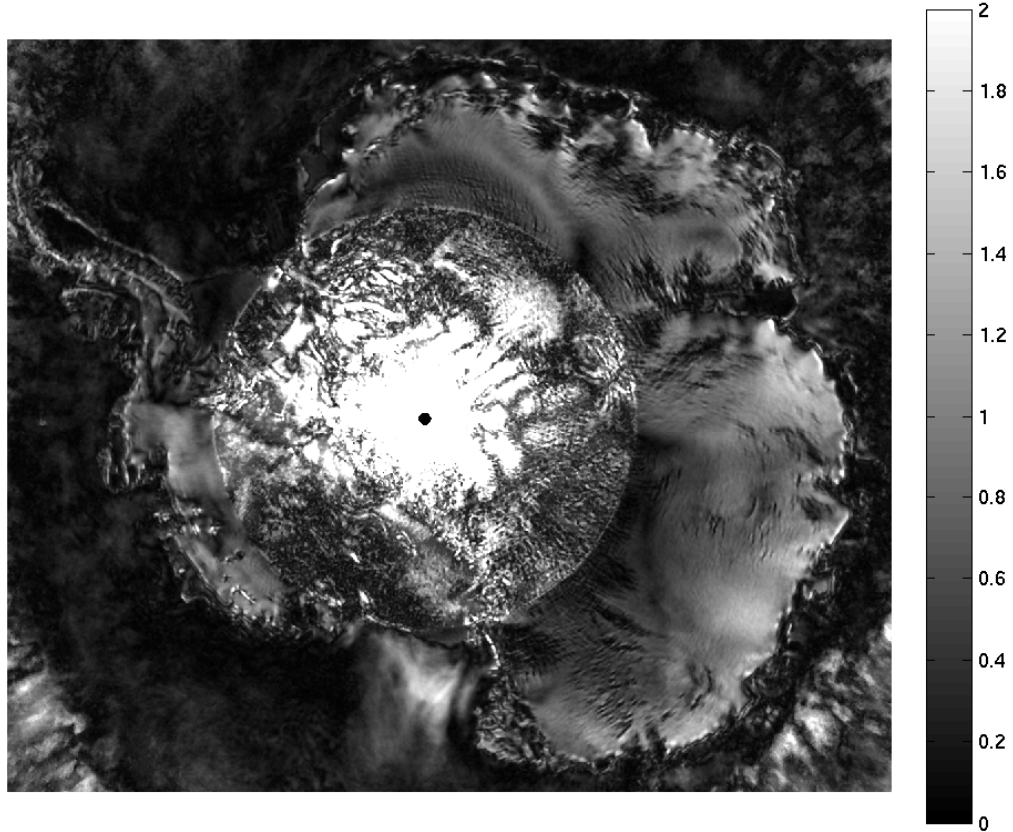


Fig. A.3 ASCAT C-band first-order azimuth modulation magnitude parameter in dB (termed 'q'). Note that due to the ASCAT antenna beam and orbit geometry, the accuracy of parameters estimated for latitudes less than approximately 78.25S falls off.

ASCAT H-pol r (1st Az Har phase) (msfa-q-Ant10-182-212.sir) in deg



Fig. A.4 ASCAT C-band first-order azimuth modulation direction parameter in deg (termed 'r'). Note that due to the ASCAT antenna beam and orbit geometry, the accuracy of parameters estimated for latitudes less than approximately 78.25S falls off.

ASCAT H-pol s (2nd Az Har) (msfa-s-Ant10-182-212.sir) in dB

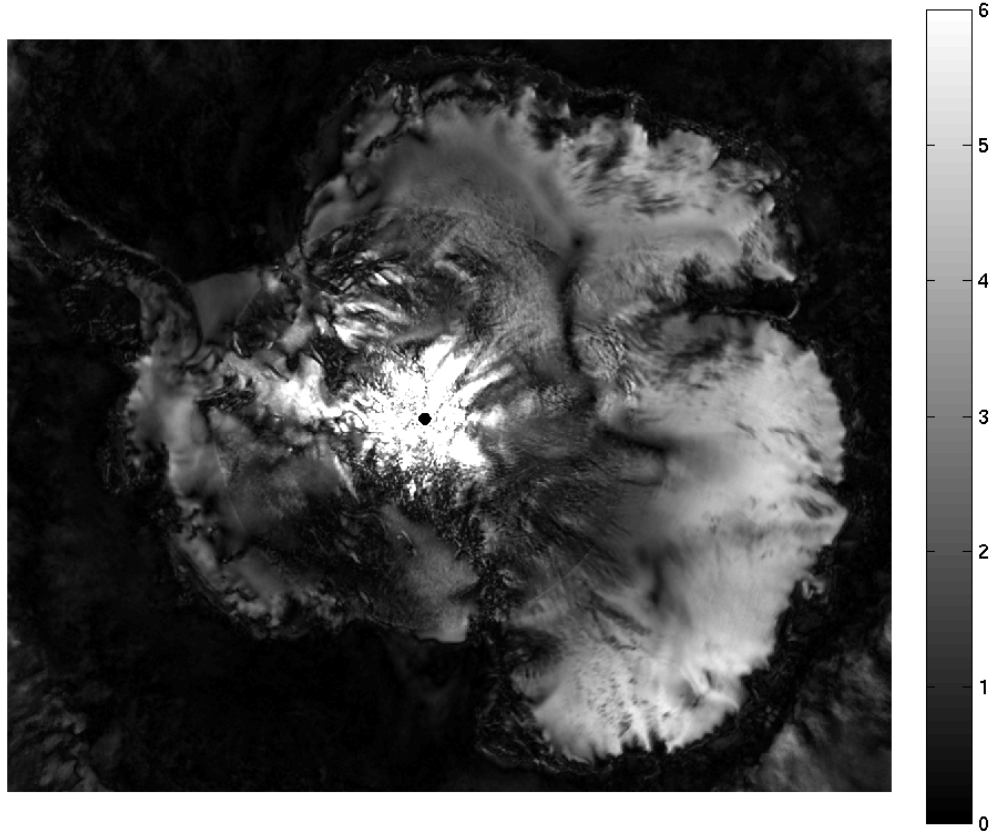


Fig. A.5 ASCAT C-band second-order azimuth modulation magnitude parameter in dB (termed 's'). Note that due to the ASCAT antenna beam and orbit geometry, the accuracy of parameters estimated for latitudes less than approximately 78.25S falls off.

ASCAT H-pol t (2nd Az Har phase) (msfa-t-Ant10-182-212.sir) in deg

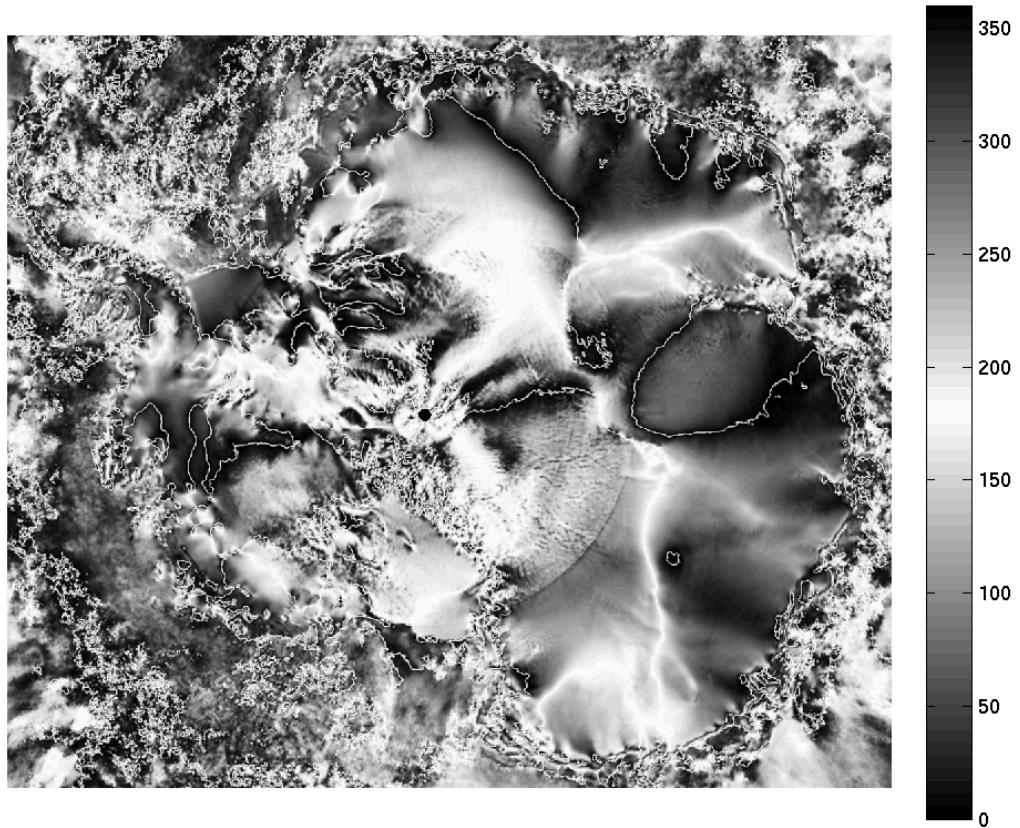


Fig. A.6 ASCAT C-band second-order azimuth modulation direction parameter in deg (termed 't'). Note that due to the ASCAT antenna beam and orbit geometry, the accuracy of parameters estimated for latitudes less than approximately 78.25S falls off.

ASCAT H-pol Q (3rd Az Har) (msfa-Q-Ant10-182-212.sir) in dB

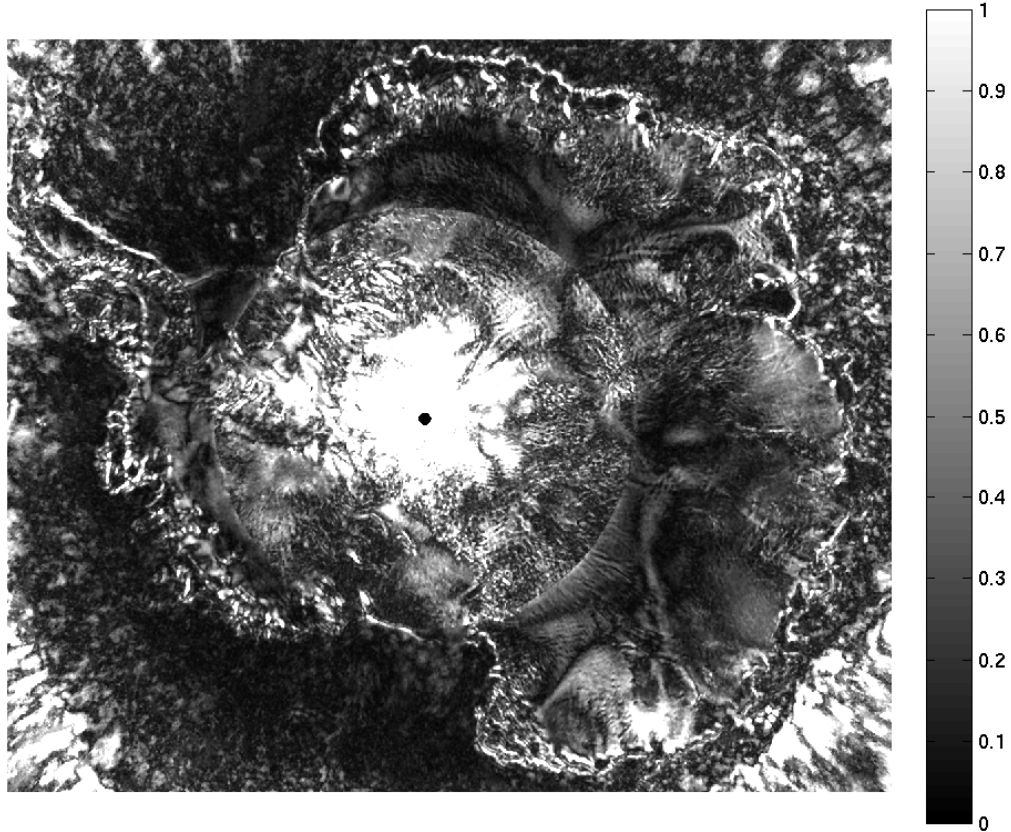


Fig. A.7 ASCAT C-band third-order azimuth modulation magnitude parameter in dB (termed 'Q'). Note that due to the ASCAT antenna beam and orbit geometry, the accuracy of parameters estimated for latitudes less than approximately 78.25S falls off.

ASCAT H-pol R (3rd Az Har phase) (msfa-R-Ant10-182-212.sir) in deg

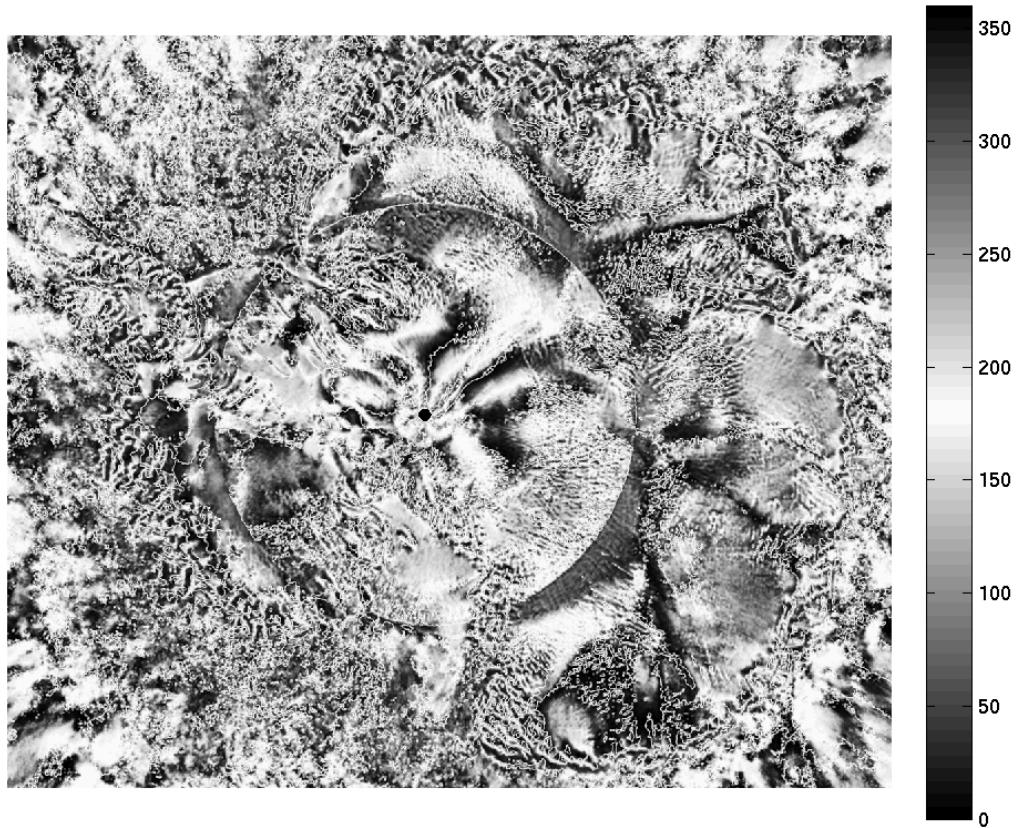


Fig. A.8 ASCAT C-band third-order azimuth modulation direction parameter in deg (termed 'R'). Note that due to the ASCAT antenna beam and orbit geometry, the accuracy of parameters estimated for latitudes less than approximately 78.25S falls off.

ASCAT H-pol S (4th Az Har) (msfa-S-Ant10-182-212.sir) in dB

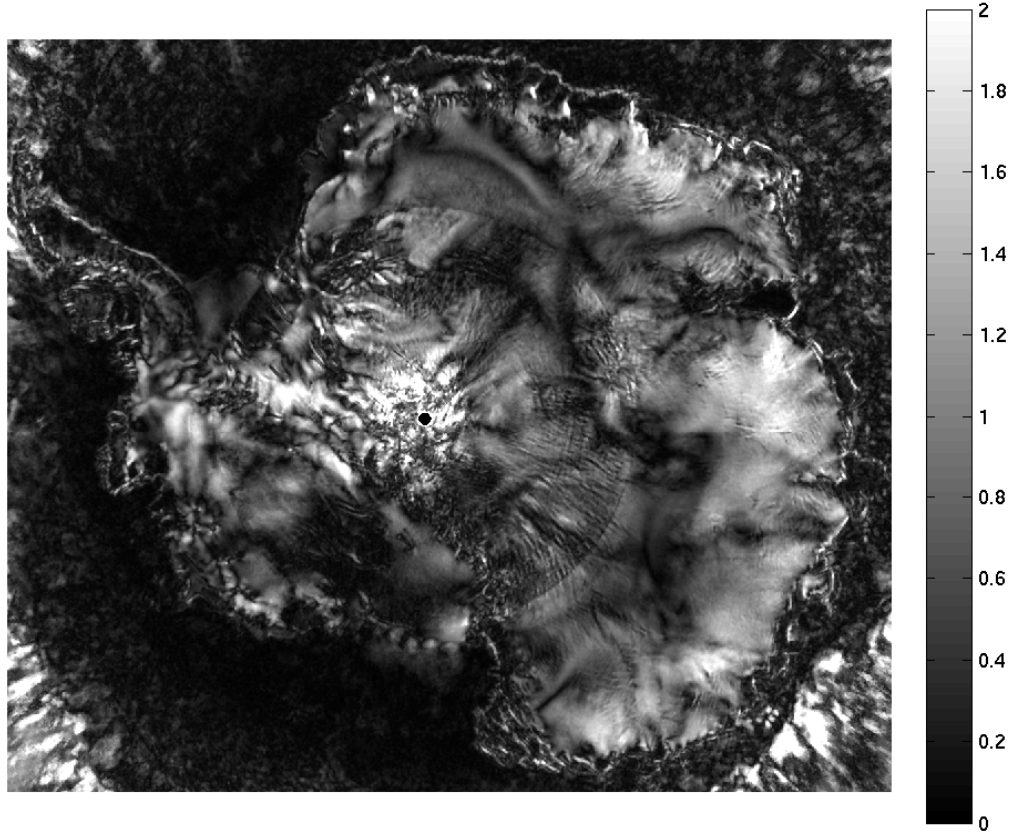


Fig. A.9 ASCAT C-band fourth-order azimuth modulation magnitude parameter in dB (termed 'S'). Note that due to the ASCAT antenna beam and orbit geometry, the accuracy of parameters estimated for latitudes less than approximately 78.25S falls off.

ASCAT H-pol T (4th Az Har phase) (msfa-T-Ant10-182-212.sir) deg

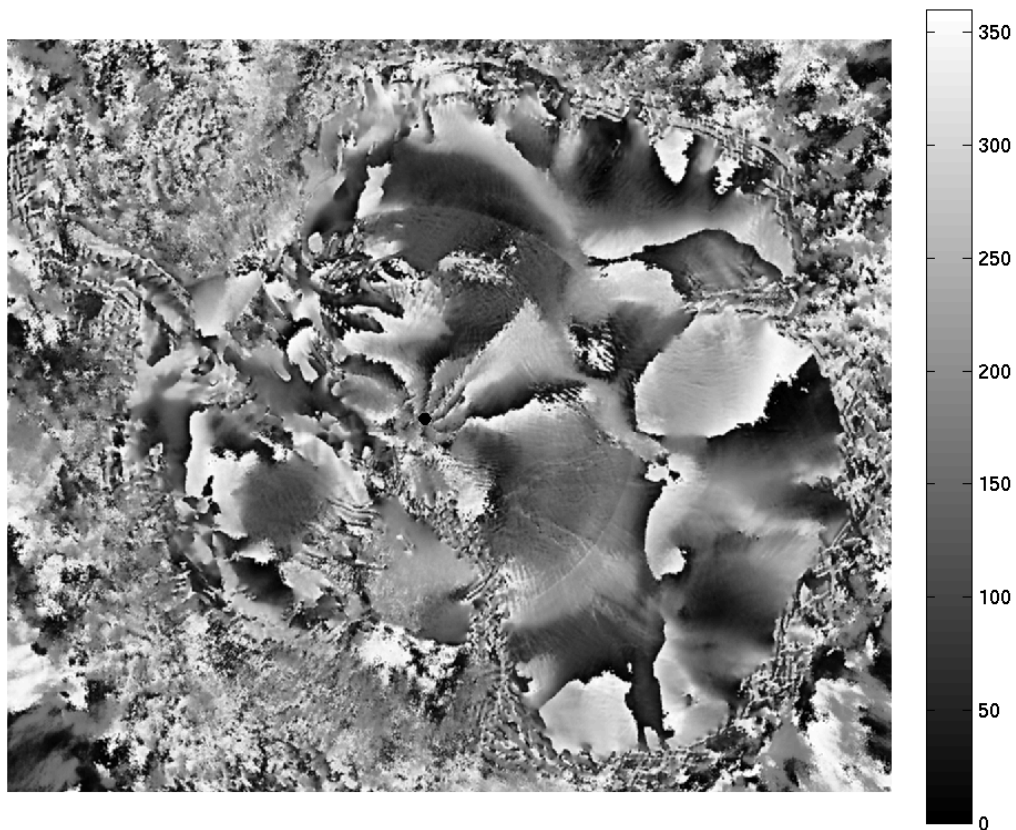


Fig. A.10 ASCAT C-band fourth-order azimuth modulation direction parameter in deg (termed 'T'). Note that due to the ASCAT antenna beam and orbit geometry, the accuracy of parameters estimated for latitudes less than approximately 78.25S falls off.